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Verification of ensemble streamflow forecasts using the Ensemble Verification System (EVS)

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Overview

- 1. Brief review of the NWS HEFS
- Two approaches to generating ensembles
- "Bottom-up" (ESP) vs. "top down" (HMOS)
- 2. Verification of streamflow ensembles
- Techniques and metrics
- Ensemble Verification System (EVS)
- 3. Example: ESP-GFS from CNRFC



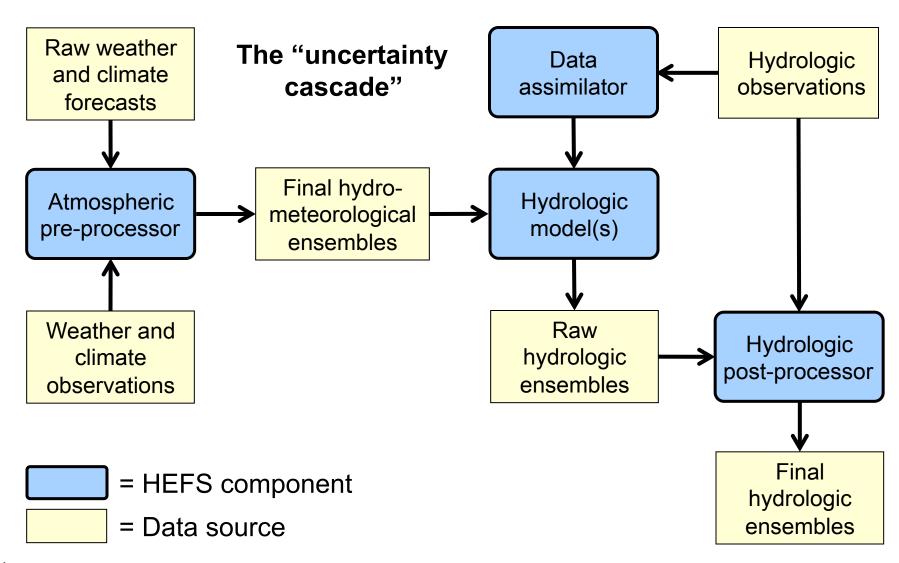


1.Brief review of the NWS HEFS





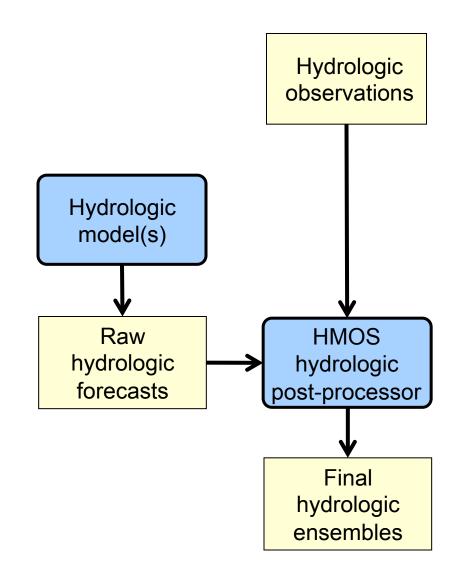
Bottom-up ("ESP")







Top down (HMOS)



= HEFS component = Data source





Pros and cons of "ESP"

Pros

- Knowledge of uncertainty sources
- Can lead to targeted improvements
- Dynamical propagation of uncertainty

Cons

- Complex and time-consuming
- Always residual bias (need post-processing)
- Manual intervention is difficult (MODs)





Pros and cons of HMOS

Pros

- Simple statistical technique
- Produces reliable ensemble forecasts
- Uses single-valued (e.g. MOD'ed) forecasts

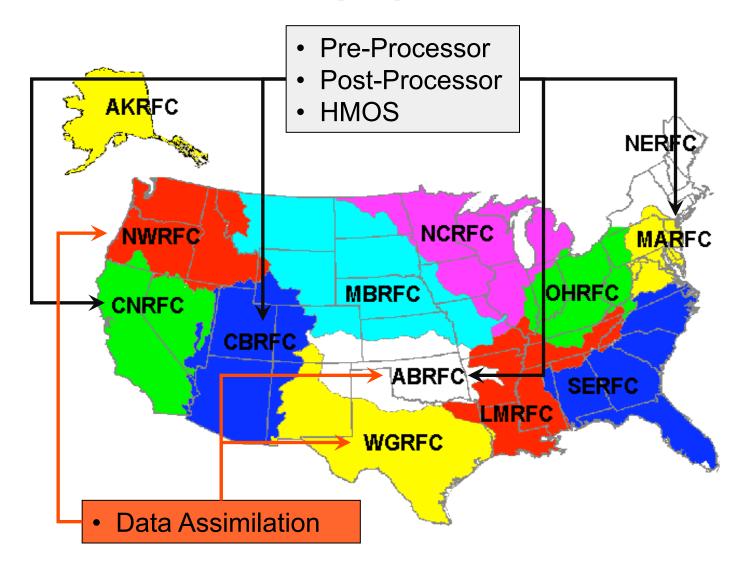
Cons

- Requires statistical assumptions
- Benefits are often short-lived (correlation)
- Lumped treatment (no source identification)





Status of X(H)EFS testing







2. Verification of streamflow ensembles

A "good" flow forecast is..?

Statistical aspects

- Unbiased (many types of bias....)
- Sharp (doesn't say "everything" possible)
- Skilful relative to baseline (e.g. climatology)

User aspects (application dependent)

- Sharp
- Warns correctly (bias may not matter)
- Timely and cost effective





Statistical aspects

Distribution-oriented verification

- Q is streamflow, a random variable.
- Consider a discrete event (e.g. flood): $\{Q > q_v\}$.
- Forecast (y) and observe (x) many flood events. $y_i = Pr[Q > q_v], \quad x_i = \{1 \text{ if } Q > q_v, \text{ else } 0\} \ i = 1,...,n$

How good are our forecasts for {Q>q_v}?

- Joint distribution of forecasts and observations
- f(x,y) = a(x|y) · b(y) "calibration-refinement"
- $f(x,y) = c(y|x) \cdot d(x)$ "likelihood-base-rate"

(Some) attributes of quality

Calibration-refinement: a(x|y)-b(y)

- Reliable if (e.g.): $E[x | y = p] = p \forall p$
- "When y = 0.2, should observe 20% of time"
- Sharp if: y → 0 or 1
- "Maximize sharpness subject to reliability"

Likelihood-base-rate: c(y|x)-d(x)

- <u>Discriminatory</u> if (e.g.):
 E[y | x = 1] >> E[y | x = 0]
- "Forecasts easily separate flood from no flood"

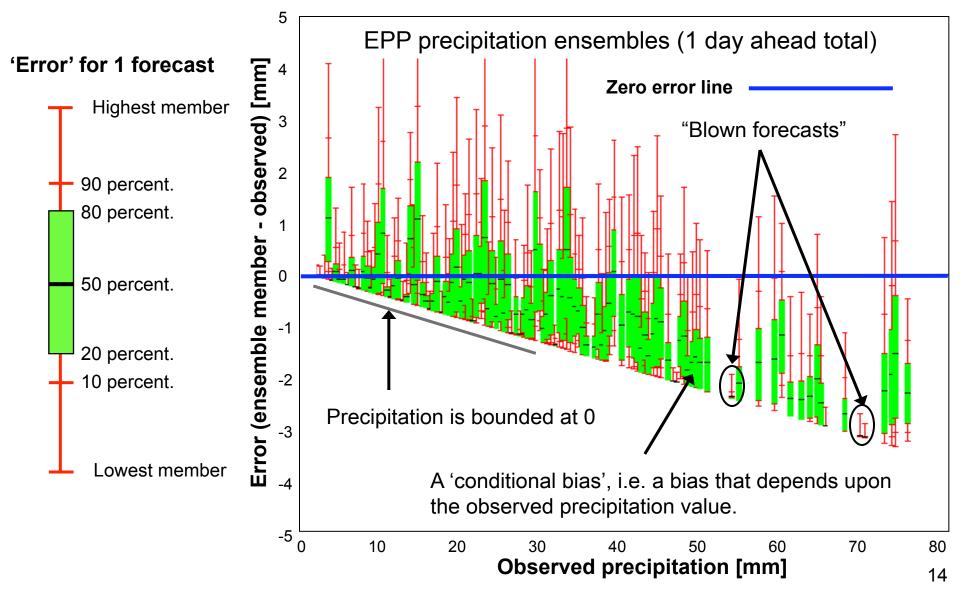




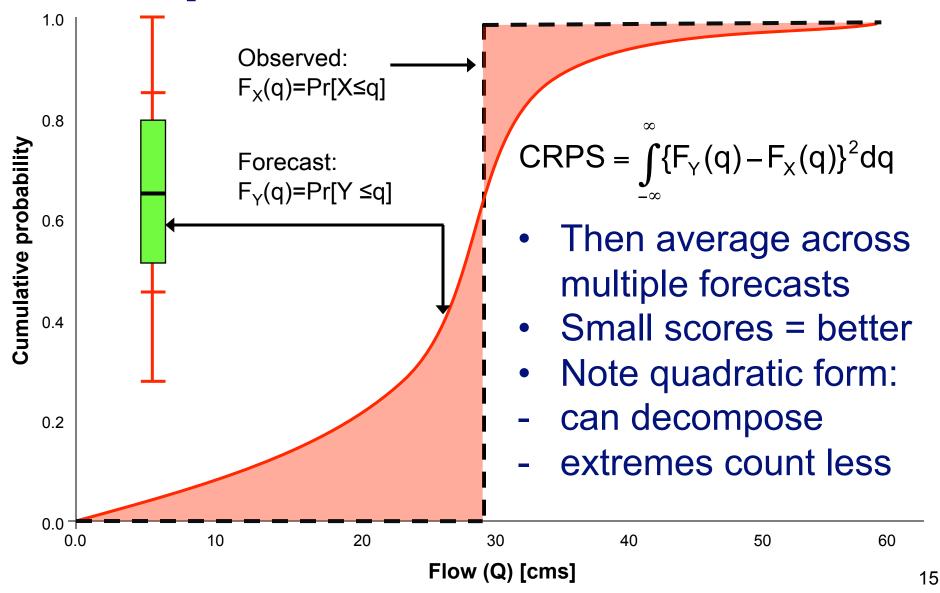
(Some) quality metrics

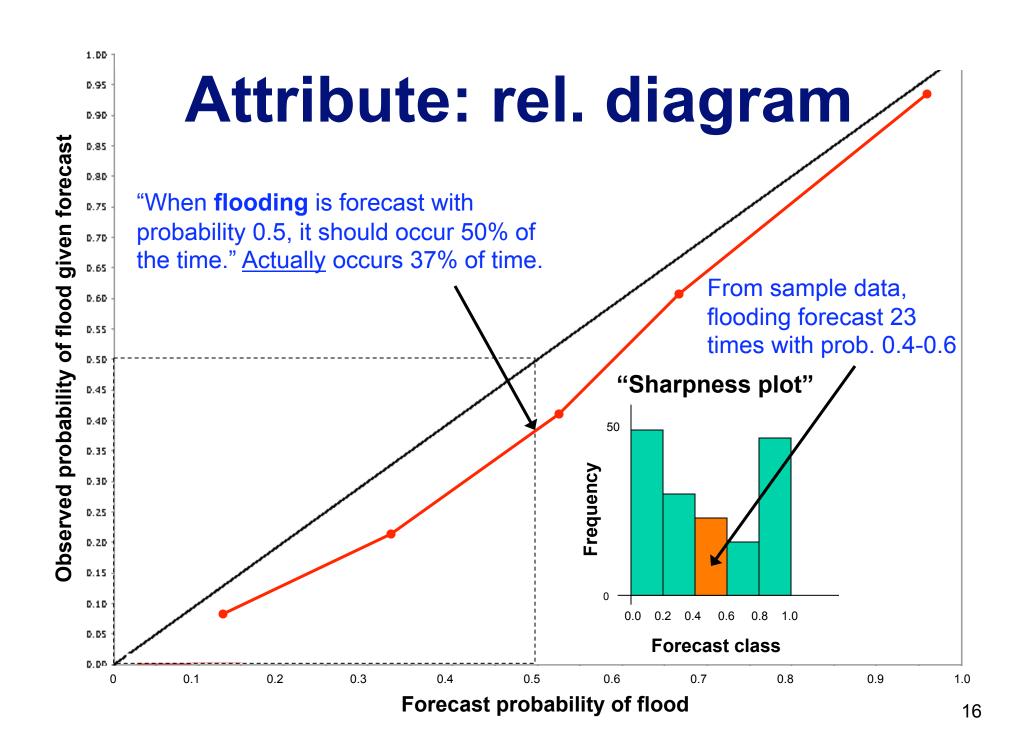
- 1. Exploratory metrics (plots of pairs)
- 2. Lumped metrics or 'scores'
- Lumps all quality attributes (i.e. overall error)
- Often lumped over many discrete events
- Include <u>skill</u> scores (performance over baseline)
- 3. Attribute-specific metrics
- Reliability Diagram (reliability and sharpness)
- ROC curve (event discrimination)

Exploratory metric: box plot



Lumped metric: Mean CRPS









The Ensemble Verification System (EVS)

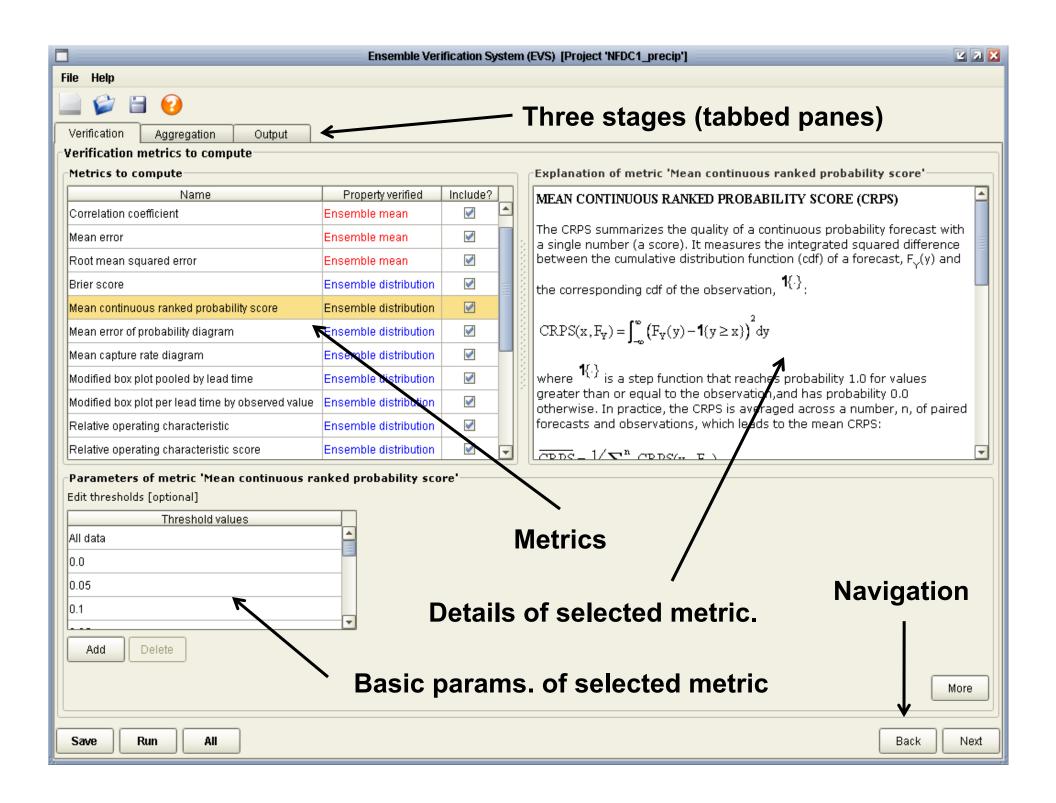




The EVS

Java-based tool

- GUI and command line. GUI is structured....
- 1. Verification (at specific locations)
- Add locations, data sources, metrics etc.
- 2. Aggregation (across locations)
- Compute aggregate performance
- 3. Output (graphical and numerical)



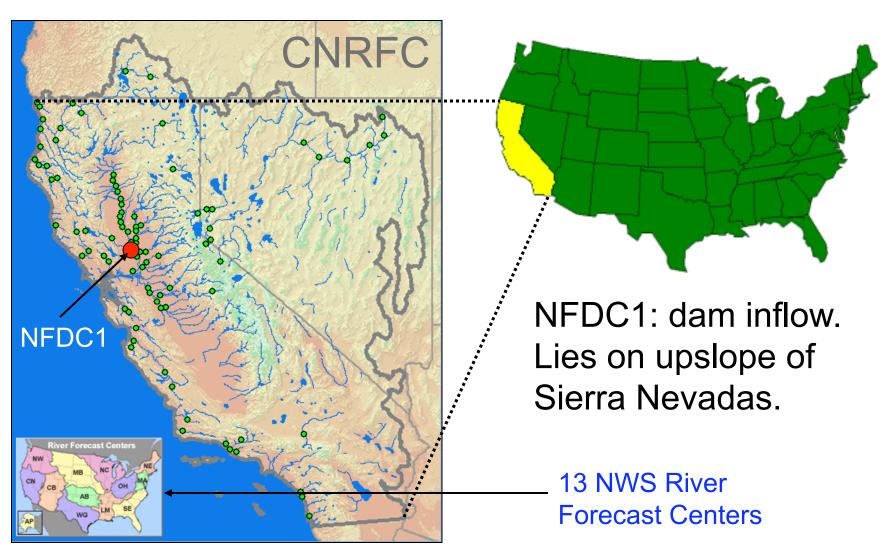




3. Example application



N. Fork, American (NFDC1)







Data available (NFDC1)

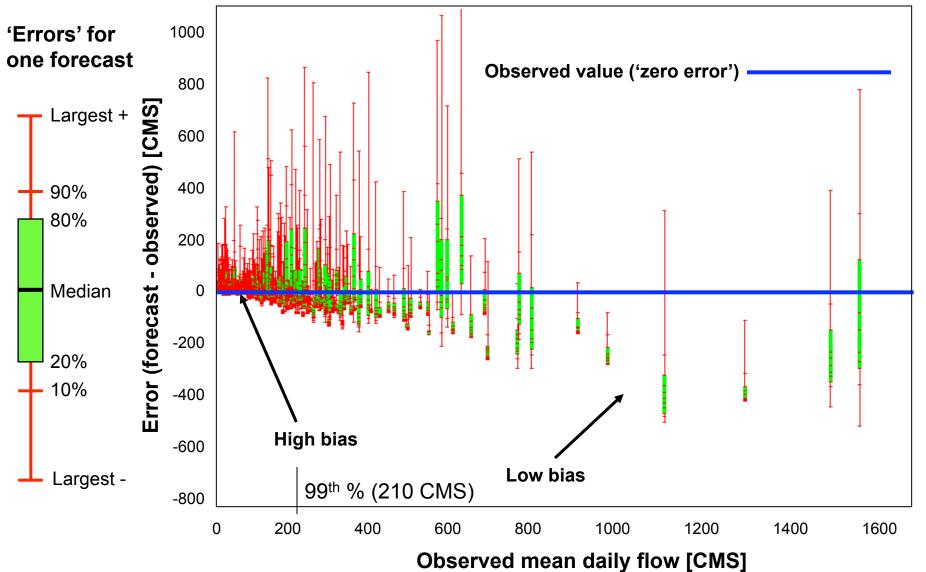
Streamflow ensemble forecasts

- Ensemble Streamflow Prediction system
- NWS RFS (SAC) w/ precip./temp. ensembles
- Hindcasts of mean daily flow 1979-2002
- Forecast lead times 1-14 days ahead
- NWS RFS (SAC) is well-calibrated at NFDC1

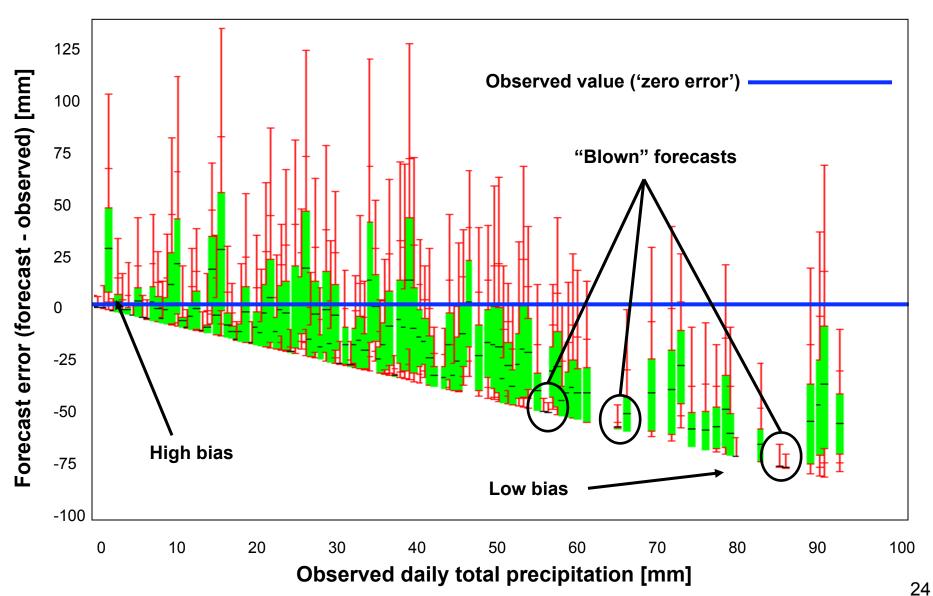
Observed daily flows

- USGS daily observed stage
- Converted to discharge using S-D relation

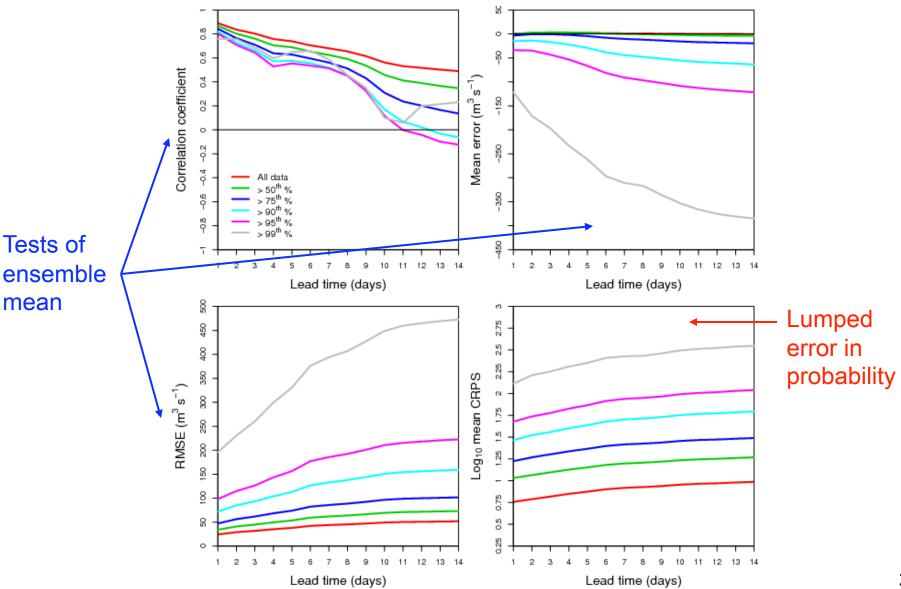
Box plot of flow errors (day 1)



Precipitation (day 1, NFDC1)



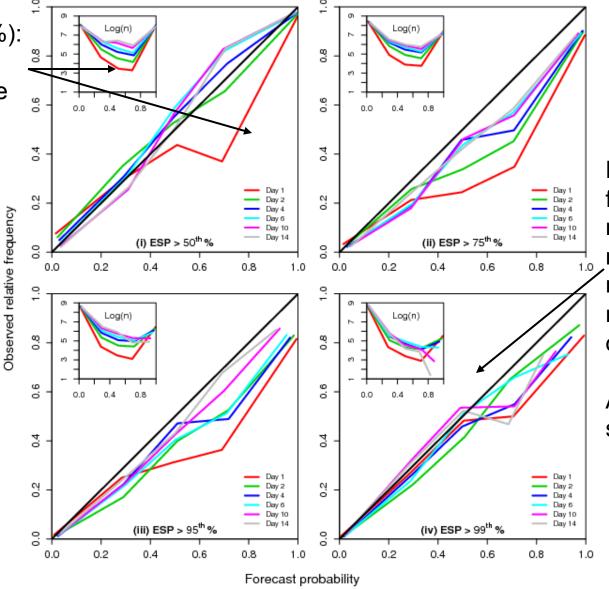
Lumped error statistics



Reliability

Day 1 (>50th%): sharp, but a little unreliable (contrast day 14).

No initial condition uncertainty (all forcing).



Day 14 (>99th%): forecasts remain reasonably reliable, but note 99% = only 210 CMS.

Also note sample size.





Next steps

To make EVS widely used (beyond NWS)

- Public download available (see next slide)
- Published in EM&S (others on apps.)

Ongoing research (two examples)

- 1) Verification of severe/rare events
- Will benefit from new GEFS hindcasts
- 2) Detailed error source analysis
- Hydrograph timing vs. magnitude errors (e.g. Cross-Wavelet Transform)



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The Ensemble Verification System (EVS) [Revised: November 12, 2009]

Overview of the EVS

The EVS is designed for verifying ensemble forecasts of hydrologic and hydrometeorological variables, such as temperature, precipitation, streamflow, and river stage, issued at discrete forecast locations (points or areas). It is an experimental prototype developed by the Hydrological Ensemble Prediction group of the Office of Hydrologic Development.

The EVS is a Java application and will run on any operating system with a suitable Java Virtual Machine (it is currently tested on Linux and Windows). It is intended to be flexible, modular, and open to accommodate enhancements and additions by its developers and users. As such, we welcome your participation in the continuing development of the EVS toward a versatile and standardized tool for ensemble verification. The software is currently provided without technical support outside of the NWS. However, we welcome collaborations, suggestions and bug reports, for which a reporting template is provided with the distribution.

Reference Papers

- Brown, J.D., Demargne, J., Liu, Y. and Seo, D.J., 2009: The Ensemble Verification System (EVS): a software tool for verifying ensemble forecasts of hydrometeorological and hydrologic variables at discrete locations. Submitted to Environmental Modelling and Software.
- Demargne, J., Brown, J.D., Liu, Y., Seo, D.J., Wu, L., Toth, Z., and Zhu, Y., 2009: Diagnostic verification
 of hydrometeorological and hydrologic ensembles. Submitted to Atmospheric Science Letters.

Release History

- EVS Version 1.0: released in May 2008.
- EVS Version 2.0: released in October 2009.

Downloads

Version	Full Download	User's Manual	Executable	Release Notes	Test Data	Source Code	Developer Docs.	Bug Template
2.0 (10/16/09)	(25.4 MB)	(2.4 MB)	(13.3 MB)	(54 KB)	(1.7 MB)	(7.1 MB)	(1.5 MB)	(2 KB)

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www.nws.noaa.gov/oh/evs.html

www.weather.gov/oh/XEFS/

Relevant published material.

Full download; user's manual (100 pp.); source code; test data; developer documentation etc.

Main Link Categories:

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Follow-up literature

- Bradley, A. A., Schwartz, S. S. and Hashino, T., 2004: Distributions-Oriented Verification of Ensemble Streamflow Predictions. *Journal of Hydrometeorology*, **5(3)**, 532-545.
- Brown, J.D., Demargne, J., Liu, Y. and Seo, D-J (submitted) The Ensemble Verification System (EVS): a software tool for verifying ensemble forecasts of hydrometeorological and hydrologic variables at discrete locations. Submitted to *Environmental Modelling and* Software. 52pp.
- Gneiting, T., F. Balabdaoui, and Raftery, A. E., 2007: Probabilistic forecasts, calibration and sharpness. *Journal of the Royal Statistical Society Series B: Statistical Methodology*, **69**(2), 243 268.
- Hsu, W.-R. and Murphy, A.H., 1986: The attributes diagram: A geometrical framework for assessing the quality of probability forecasts. *International Journal of Forecasting*, **2**, 285-293.
- Jolliffe, I.T. and Stephenson, D.B. (eds), 2003: Forecast Verification: A Practitioner's Guide in Atmospheric Science. Chichester: John Wiley and Sons, 240pp.
- Mason, S.J. and Graham N.E., 2002: Areas beneath the relative operating characteristics (ROC) and relative operating levels (ROL) curves: Statistical significance and interpretation, *Quarterly Journal of the Royal Meteorological Society*, **30**, 291-303.
- Murphy, A. H. and Winkler, R.L., 1987: A general framework for forecast verification. *Monthly Weather Review*, **115**, 1330-1338.
- Wilks, D.S., 2006: *Statistical Methods in the Atmospheric Sciences, 2nd ed.* Academic Press, 627pp.





Additional slides





Verification metrics

Metric name	Quality tested	Discrete events?	Detail
Mean error	Ensemble mean	No	Lowest
RMSE	Ensemble mean	No	Lowest
Correlation coefficient	Ensemble mean	No	Lowest
Brier Score	Lumped error score	Yes	Low
Brier Skill Score	Lumped error score vs. reference	Yes	Low
Mean CRPS	Lumped error score	No	Low
Mean CRPS reliability	Lumped reliability score	No	Low
Mean CRPS resolution	Lumped resolution score	No	Low
CRPSS	Lumped error score vs. reference	No	Low
ROC score	Lumped discrimination score	Yes	Low
Mean error in prob.	Reliability (unconditional bias)	No	Low
Spread-bias diagram	Reliability (conditional bias)	No	High
Reliability diagram	Reliability (conditional bias)	Yes	High
ROC diagram	Discrimination	Yes	High
Modified box plots	Error visualization	No	Highest

